





RoboCupJunior 2013 Dance: Dance/ Theatre performance Score Sheet

Team name Secondary / Primary Dance / Theatre Judge's initials

Choreography and Story-telling (10 marks)	
Dance >> Robot(s) performance used interesting, engaging and/or artistic dance movements	
Theatre >> Robot(s) performance used interesting and/or engaging movements which told a story	/2
Dance >> Robot(s) move rhythmically to the music:	
Robot(s) movements do not match the music = 0; some match to the music = 1/2; complements the music = 3.	
Theatre >> Robot(s) told a story whilst moving to music:	
Robot(s) movements do not match the music = 0; some match to the music = 1/2; complements the music = 3.	/3
Dance >> Robot(s) made use of the allocated dance space creatively to enhance the dance	
Theatre >> Robot(s) made use of the allocated dance space creatively to tell a story	/2
Included more difficult movements/sequences as the team took risks:	
Robot performs basic movements = 1; Examples of movements to be rewarded: risking balance, coordination between multiple robots, sequencing robot movement to an event, etc.	/3
Sub-Total	
	/10
Entertainment Value (10 marks)	
Performance engages the audience:	/2
An overall theme and atmosphere was created, exciting, entertaining, enthralling, humorous, etc.	/3
Props, scenery, humans costumes, human interaction or dancing complemented robot(s) performance: Does human interaction , props and scenery ADD to robot(s) performance or DISTRACT from it?	/3
Robot appearance complements the performance	/2
Additional technology: lights/moving parts/sound or light effects complements the performance.	/2
Sub-Total	/10
Introduction and Presentation (6 marks)	/2
Introduction use of setup to explain the robotic technologies used in the performance	/2
Digital presentation used to enhance robotic performance: Reward creative presentations that enhance the overall performance.	/4
Sub-Total	/6
Sensors used in the performance (2 marks) *other sensor marks in technical interview	
Sensors used in the performance as described in the technical interview: Distance sensors used for detection of props or other robots,	
compass used for exact turns, encoders used for moving exact distances, communication among robots etc.	/2
Sub-Total	/2
Execution of performance (12 marks)	
Robot(s) were reliable and performed as expected (did not 'go wrong')	/3
Robot(s), props, scenery including costumes and decorations were stable and did do not fall apart	/3
Was performed without restarts, human intervention, robot stays within the defined dance area and within the allotted time	
(including restarts), marks are removed for:	
Human intervention: -1 for each unplanned human contact Particle of formula the state of the provided provided provi	
 Restarts: -1 for each restart (excluding music miscues or factors outside control of team) Allotted time: 5 mins max: dance > 1 min, < 2 mins. Reduce score by 1 for every 10 sec over 5 min overall. 	
Within area: -1 for each infraction of the stage boundary.	/6
Sub-Total	/12
Marks allocated at the judge's discretion (10 marks)	,
Reward creative, innovative, entertaining robotic performance demonstrating an inspiring or innovative use of technologies. Use	
notes below to briefly explain reason.	/10
Sub-Total	/10
Sub-Total	/10

TOTAL SCORE /50

Recommend for certificate:

- Programming
- **★** Construction
- **■** Use of Sensors
- **≰** Electronics

- Choreography
- **€** Costume
- entertainment Vale
- **★** Best Creative Presentation