



# CoSpace Theatre and Dance Interview

Team Name: \_\_\_\_\_  
 Country: \_\_\_\_\_

Judge Initial: \_\_\_\_\_

SECTION 1: ROBOT DESIGN, CONSTRUCTION AND PROGRAMMING (19 MARKS)		POINTS
1.1	<b>Real robot(s) design, construction</b>	
	<ul style="list-style-type: none"> <li>▪ <i>Robots are designed and constructed by the students (opposed to standard kits)</i> <ul style="list-style-type: none"> <li>✦ Pre-constructed robot = 0;</li> <li>✦ Robot with a set of building instructions = 1;</li> <li>✦ Commercial kit or Lego with creative construction = 1 - 2;</li> <li>✦ Own design and hand-built = 2;</li> </ul> </li> </ul>	<b>/2</b>
	<ul style="list-style-type: none"> <li>▪ <i>Mechanical construction and robot reliability:</i> <ul style="list-style-type: none"> <li>✦ Reward design for complexity if it aids robot movement, such as gearing, linkages, pivots, motors are used in design and drive mechanisms</li> </ul> </li> </ul>	<b>/3</b>
1.2	<b>Electronic hardware, sensors and other technologies</b>	
	<ul style="list-style-type: none"> <li>▪ <i>Electronic hardware</i> <ul style="list-style-type: none"> <li>✦ Use of commercial kit, such as Lego NXT, and understanding of its operation (eg. Input, output, power, memory, processor, etc)</li> <li>✦ Home built circuitry and able to describe their operation (eg. Functions of each board, voltage regulatory, motor speed adjustment, etc)</li> </ul> </li> </ul>	<b>/2</b>
	<ul style="list-style-type: none"> <li>▪ <i>Effective use of sensors</i> <ul style="list-style-type: none"> <li>✦ Able to install sensors on the robot and understand their function and operation (eg. Type of sensors used, Working principal, etc.)</li> <li>✦ Able to use sensors creatively and effectively or in different ways (e.g. line tracking = 1, more creative use of sensors = 2-3)</li> </ul> </li> </ul>	<b>/3</b>
1.3	<b>Programming</b>	
	<ul style="list-style-type: none"> <li>▪ <i>Complex, innovative or original programming used appropriate to age and level of expertise, and can explain and under their program thoroughly</i> <ul style="list-style-type: none"> <li>✦ Using loops, interrupt, etc...</li> <li>✦ Able to describe what this section of program tells the robot to do and modify it as per request.</li> </ul> </li> </ul>	<b>/5</b>
1.4	<b>Innovation</b>	
	<ul style="list-style-type: none"> <li>▪ <i>Reward any innovation in real robot design that aids the performance</i></li> </ul>	<b>/4</b>
<b>Sub-total</b>		<b>/19</b>

Mentor involvement: the score can be reduced by up to 20% if we believe there has been significant mentor involvement.

SECTION 2: VIRTUAL ROBOT DESIGN AND PROGRAMMING (8 MARKS)		POINTS
<b>2.1</b>	<b>Virtual robot(s) design</b>	
	<ul style="list-style-type: none"> <li>▪ <i>Type of virtual robot</i> <ul style="list-style-type: none"> <li>✦ Use of original and innovatively designed robots. Do they add to the performance?</li> </ul> </li> </ul>	/2
<b>2.2</b>	<b>Programming</b>	
	<ul style="list-style-type: none"> <li>▪ <i>Program each robot to fit in the theatre performance.</i> <ul style="list-style-type: none"> <li>✦ How do you program each robot according to its role in the Theatre performance? How do you solve the problems encountered?</li> </ul> </li> </ul>	/4
	<ul style="list-style-type: none"> <li>▪ <i>Complex, innovative or original programming used appropriate to age group</i> <ul style="list-style-type: none"> <li>✦ Create innovative movement of both wheeled and humanoid robots.</li> <li>✦ Address the robot balancing, especially humanoid robot dancing.</li> </ul> </li> </ul>	
	<ul style="list-style-type: none"> <li>▪ <i>Students can explain, describe and understand their program thoroughly</i> <ul style="list-style-type: none"> <li>✦ Able to describe what this section of program tells the robot to do and modify it as per request.</li> </ul> </li> </ul>	/2
<b>Sub-total</b>		<b>/8</b>

SECTION 3: VIRTUAL ENVIRONMENT DESIGN (9 MARKS)		POINTS
<b>3.1</b>	<b>3D virtual environment design</b>	
	<ul style="list-style-type: none"> <li>▪ <i>The 3D props are original and creative (eg. Teams developed 3D models instead of taking from library)</i></li> <li>▪ <i>The 3D environment includes 3D models, audio, video. They are creatively embedded into the virtual world.</i></li> <li>▪ <i>The virtual environment matches the theme of the performance. The overall layout presents a piece of artwork</i></li> </ul>	/5
<b>3.2</b>	<b>Drama editor</b>	
	<ul style="list-style-type: none"> <li>▪ <i>How scenes were shot and composed. Reward to the creative use of camera and lighting (eg. use disco light creatively, zoom-in, zoom-out to realize the scene in accordance with the theatre performance.)</i></li> <li>▪ <i>How scenes were edited? Reward to the complex sequence designed. Eg. creative use of music, video, virtual/virtual communication, virtual/real communication, real robots, virtual robots, etc)</i></li> </ul>	/4
<b>Sub-total</b>		<b>/9</b>

SECTION 4: COMMUNICATION (5 MARKS)		POINTS
<b>4.1</b>	<ul style="list-style-type: none"> <li>▪ <i>Understand and able to configure the communication</i></li> <li>▪ <i>Able to establish the communicate between virtual robots/real robots/virtual objects</i></li> </ul>	
<b>Sub-total</b>		<b>/5</b>

SECTION 5: EVIDENCE OF AUTHENTICITY (4 MARKS)		POINTS
<b>5.1</b>	<ul style="list-style-type: none"> <li>▪ <i>Photographs of different stages of development; Logbook; journal; photographic record or similar documents</i></li> <li>▪ <i>Students successfully address problems they have faced (eg. How did you stop x from becoming loose during the performance? What have you done to prevent your robot(s) from falling over, or breaking if they fall?, how did you design the virtual robot, etc.)</i></li> </ul>	
<b>Sub-total</b>		<b>/4</b>

**Total Score: /45**